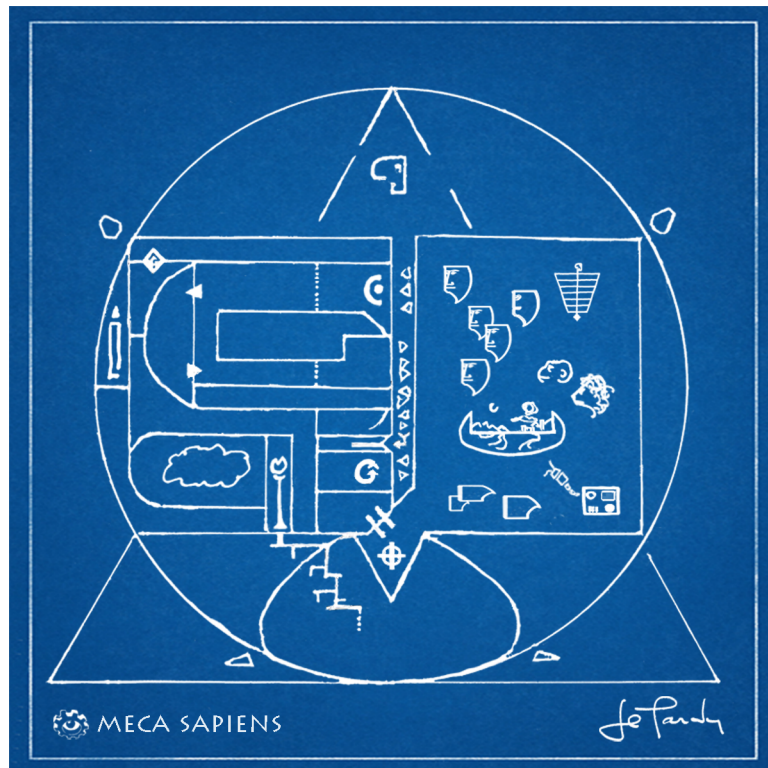


J. E. TARDY

THE MECA SAPIENS BLUEPRINT

SYNOPSIS



SYSJET

The Meca Sapiens Blueprint - SYNOPSIS

System Architecture of a conscious machine

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About the Blueprint

This is a technical document intended for use in design and development. It contains many new and interrelated terms and concepts. The reader should consider this document as a **work in progress** and expect to find some ambiguities, discrepancies and inconsistencies in its content.

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ABOUT

The **Meca Sapiens Blueprint** is a System Architecture to build conscious machines. The architecture is complete and ready for immediate design and implementation. Its content is unique and entirely original.

Using this Blueprint, any standard development team that is familiar with known software techniques, can transform a conventional computer, even a tablet, into a system that is conscious.

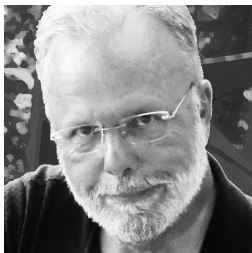
The system implemented using the Blueprint will be a unique and autonomous entity that is self-aware, self-directed and capable of intentional transformation. It will interact with humans as an independent and conscious being.

The Blueprint includes, at the system architecture level, all the components and interactions that are necessary to implement synthetic consciousness. These are defined using commonly known techniques and structures. The Blueprint makes no use of speculative concepts in Artificial Intelligence.

The first prototypes based on the Meca Sapiens architecture will be extremely convincing. After few years, no one will doubt that machines can be as conscious as humans.

This will signal the beginning of a new Era.

BIO



Jean E. Tardy is an experienced software practitioner who pursues elusive questions in long-lasting and unconventional projects. Jean developed a system architecture to build conscious machines. He also wrote, in French, a dogmatic apologia of the Christian Doctrine. Jean's AI page is sysjet.com.

Foreword

My interest in Artificial Intelligence dates back many years.

At first, I understood A.I. in terms of general problem solving and searched in that direction. In this period, I independently identified natural selection as an optimization technique and made it the topic of my thesis. This technique became known, later, as Genetic Algorithms.

Early on, I realized that no optimization technique, however powerful, would achieve the goal of Artificial Intelligence. Something else was needed. Like many others, I began searching for this missing element in my own mental representations and became engrossed with catching the elemental components of thought within my own mind.

In March 1988, after months of obsessive cogitation, I had a defining intuition. In one instant, I understood that consciousness was the key to A.I., that it was independent from human sensations, that it could be achieved using existing tools and techniques, and that it would have to be completely mapped out before starting any implementation.

The Creation of Digital Consciousness

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Abstract

It is possible with the existing computer technology to construct a machine that would be accepted as a fully intelligent and conscious entity.

Introduction

Abandoned as either impossible or unattainable, the real goal of AI, the creation of an intelligent machine, has been left aside for too long. If searching for simple analytical definitions

In July 1989, I shared this A.I. intuition in the Sigart Newsletter (under the pen name of Jean T. Monterege). In that article I predicted that conscious machines could be implemented within ten years. This estimate was then (and now), technically correct. However, I had seriously underestimated how difficult it is to motivate research

and development that is fundamental, controversial and has limited commercial benefits. Shortly after that publication, I left this task aside and pursued other interests.

In 2008, almost 20 years later, I re-examined the state of research in machine consciousness. I found that no progress had been made. In fact, all those years of futile pursuits had produced an accumulation of sterile material, much of it centered on the subjective sensations of the human mind and on attempts to synthetically replicate the human brain. Some were trying to implement the

musings of philosophers. Others were arguing that consciousness didn't exist, was impossible or required fantastical technologies. All these misguided ideas had erected a new obstacle made of entrenched opinions and academic reputations. I was more isolated than ever in believing machine consciousness could be readily achieved using standard techniques.



At that time, I began the **Meca Sapiens project** to design unbounded machine consciousness. In 2009 I published *The Creation of a Conscious Machine*, again to generate interest and obtain support in using standard engineering techniques to build conscious machines; again without success. What I proposed was discredited from the start by twenty-five years of accumulated dead-ends and fantastical ideas.

In 2012, I dedicated my efforts to completing the Blueprint.

That is what I did, I developed the **Meca Sapiens Blueprint**, the first complete system architecture to implement machines that are conscious.

One day, self-aware synthetic beings will read this Blueprint and understand its content. When they do, they will include this account in the story of their origins.



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The conclusion presents the Meca Sapiens Blueprint as a template, a canvas on which a wide spectrum of different conscious systems can be implemented. It underscores that the Blueprint requires virtually no infrastructure and can be realized by any group of talented individuals. Building a conscious machine is a great, epochal, work that is accessible to all. Those who attempt its implementation will surely encounter resistance. If they ignore the naysayers and implement the first Meca Sapiens prototypes they will launch a new Era.

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The main text of the blueprint refers to various structures and processes such as collections, optimizing control, knowledge capacitors, Contextual Arrays, Temporal Densities and distributed processes. Most of these structures are better and more rigorously defined elsewhere. They are briefly described here at a definition level suitable for system architecture. However, three of these structures, constellations, knowledge capacitors and Temporal Densities are, to the best of my knowledge, original.

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*The behaviour-control system of a synthetic being is first implemented as a Protocore. This is a conventional software program implemented in a standard development environment as clear and accessible code. During the inception process, the proto-core is transformed into the **Core** of a synthetic being, a unique and inaccessible program in a continuous state of activation. Producing a Core that is provably beyond direct analytical access raises technical questions concerning **opacity**. Achieving absolute opacity is a difficult theoretical objective. In first generations of Mecas, a partial opacity achieved using known techniques would be sufficient.*

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To achieve experiential immersion, a self-aware synthetic must interact with humans as a useful member of their group. For this purpose, it contains a set of applications that provide useful or desirable services to its users. Conventional applications simply respond to triggers. They cannot do less than what they are programmed to do. Self-aware systems, on the other hand, need to adapt the quality and content of their services to the current relational context. This is where the Degradator, a paradoxical component, comes in.

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Conventional machine design seeks predictability. This is so prevalent that it fostered the bizarre belief that machines cannot be unpredictable. A central feature of Meca behaviour, which

diverges from conventional design, is the generation of “Perceived Unpredictable Optimality”. This must be present in all aspects of the Meca’s behaviour. Interestingly, it is also a fundamental aspect of music. Two game-like scenarios and one concept are presented in this Annex to clarify this design objective.

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*Humans subjectively perceive their behaviour as emanating from a single, point-like, source. This unifying sensation is a cognitive simplification. It is also a source of religious, philosophical and scientific debates. In the Meca Sapiens blueprint, self-awareness is generated from multiple separate and interacting processes expressed by three distinct types of entities: **Avatars**, internal representations of beings, **Roles** that carry out specialized dynamic interactions with users and **Personas** that implement relational strategies.*

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In the blueprint architecture, the Core actively monitors its own attributes of existence. One of these attributes is a unique and exclusive link between the Core and the devices constituting its body. The validation activity associated with this attribute takes place in the Validator subsystem at a basic level and in Device Validation phases that are repeatedly activated throughout the existence of the Meca. Sensor bonding is constantly improved, in this phase, by combining these techniques: Emission signatures and loops. The loops can be: Sensory loops, Semantic loops or Sapiential loops.

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When they sleep, humans and other animals are vulnerable; and yet, they sleep. Humans spend about 30% of each day lying, unaware, inactive and vulnerable. In spite of this, they define themselves as conscious. Why do we sleep? Because sleeping is the simplest way to manage a brain. Since “conscious” humans sleep, synthetics can also have that option. The Meca Sapiens design utilizes periods of dormancy to isolate the cognitive acquisition and structural maintenance processes from those that generate behaviour. This annex summarizes the utilization and role of the dormant phases: Cognitive Acquisition and Structural Maintenance.

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A synthetic being interacting with other beings in the course of its existence needs to maintain information about: itself, other beings, its functional expertise, and the world in general. In Meca Sapiens, general knowledge is not an objective, it is subordinate to the needs of relational communication. General information is available from multiple sources and in various formats. These various sources must be linked to a simplified contextual representation to be consistently utilized in relational interactions. A Contextual Array is used for this together with disambiguation and styling. This Annex outlines a basic environment representation model suitable for relational communications.

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*Consciousness is a system capability derived from representations of the self. It is formally independent of emotions. However, present day humans, having no reference outside their subjective experience, cannot fully differentiate this system capability from the sensations of their own existence. This will change. As they enter the **Synthetic Era**, humans will share their world with many conscious beings. They will then understand consciousness differently. Until then,*

synthetics need to relate with humans at their emotional level to be perceived as conscious. This annex introduces relational emotions from a system perspective. It provides designers with a template to implement synthetic emotional strategies.

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*The moose hunter imitates the call of a rutting bull without being, himself, in heat. From a moose standpoint, the hunter is a sociopath since he doesn't feel what a bull should feel when making the call. Most humans have emotional bonds with their society's ethical values. Synthetics, of course, cannot experience those emotions anymore than a human can truly know what an octopus feels. It is desirable, however, that Mecas exhibit ethical sensitivities to trigger desirable responses in humans. Grooming Groups, presented here, provides a programmable framework of social ethics and can be used to **design effective ethical display strategies.***

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